

### PH3111 Problems - Hamiltonian

1. Prob. 10.28

2. Prob. 10.29

3. Consider two (continuous) functions of generalized coordinates  $q_k$  and corresponding momenta,  $p_k$ , for example  $g(q_k, p_k)$  and  $h(q_k, p_k)$ . The “Poisson Bracket” is defined by

$$[g, h] \equiv \sum_k \left( \frac{\partial g}{\partial q_k} \frac{\partial h}{\partial p_k} - \frac{\partial g}{\partial p_k} \frac{\partial h}{\partial q_k} \right)$$

Show that:

(a) 
$$\frac{dg}{dt} = [g, H] + \frac{\partial g}{\partial t}$$

(b) 
$$[p_i, p_j] = [q_i, q_j] = 0$$

(c) 
$$[q_i, p_j] = \delta_{ij}$$

where  $H$  is the Hamiltonian and  $\delta_{ij} = 1$  if  $i = j$  and is zero otherwise. (Hint: if you are spending a lot of time on these, you are doing them wrong!)

#### Notes:

i. If  $[g, h] = 0$ , then  $[g, h] = [h, g]$  and we say that “ $g$  and  $h$  commute” (for this operation).

ii. If  $[g, h] = 1$ , then  $g$  and  $h$  are said to be “canonically conjugate.”

iii. (a) implies that if the quantity represented by  $g$  is not an explicit function of time, then it will be a constant of the motion as long as  $[g, H] = 0$ , that is, if  $g$  and  $H$  commute. (Notice that  $H$  may be a function of time!)

iv. (a) can be used with  $g = p_k$  and with  $g = q_k$ , along with the fact that our coordinates are not explicit functions of time, to show that

$$\dot{q}_j = [q_j, H], \quad \dot{p}_j = [p_j, H]$$